## **WEST Search History**

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DATE: Tuesday, December 27, 2005

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DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ				
	L24	correct\$3 and L23	17	
	L23	sensor and L22	31	
	L22	robot and L21	50	
	L21	bacchi.in.	166	
	L20	bacchi.in. and substrate and sensor	0	
	L19	bacchi.in. and substrate and sensor and motor	j 0	
	L18	bacchi.in. and substrate and sensor and motor and displacement	0	
	L17	bacchi.in. and substrate and sensor and motor and displacement and correct\$3	0.	
	L16	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 and position	0	
	L15	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 and position and central axis	0	
	L14	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 adn position and axis	0	
	L13	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 adn position and central axis	0	
	L12	18 and 19	61	
	L11	18 and 19 and L10	23	
	L10	central axis and L9	47825	
	L9	predetermin\$3 or "pre-defin\$3" and L8	2545811	
	L8	support and L7	65	
	L7	displacement and L6	68	
	L6	l4 and L5	95	
	L5	correct\$3 same position	330725	
⊏	L4	robot and motor and control\$3 and substrate and sensor and position and optical and capacitor and magnetic	198	
	L3	bacchi.in.	166	
	L2	yim.in. and robot and substrate	9	
	L1	10/697731	1	

**END OF SEARCH HISTORY**